

Causal Computational Models for Gene Regulatory Networks

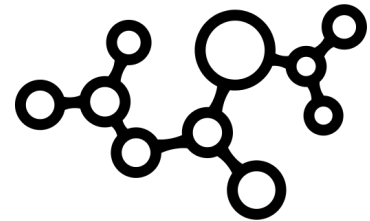
Sahil Loomba

Parul Jain

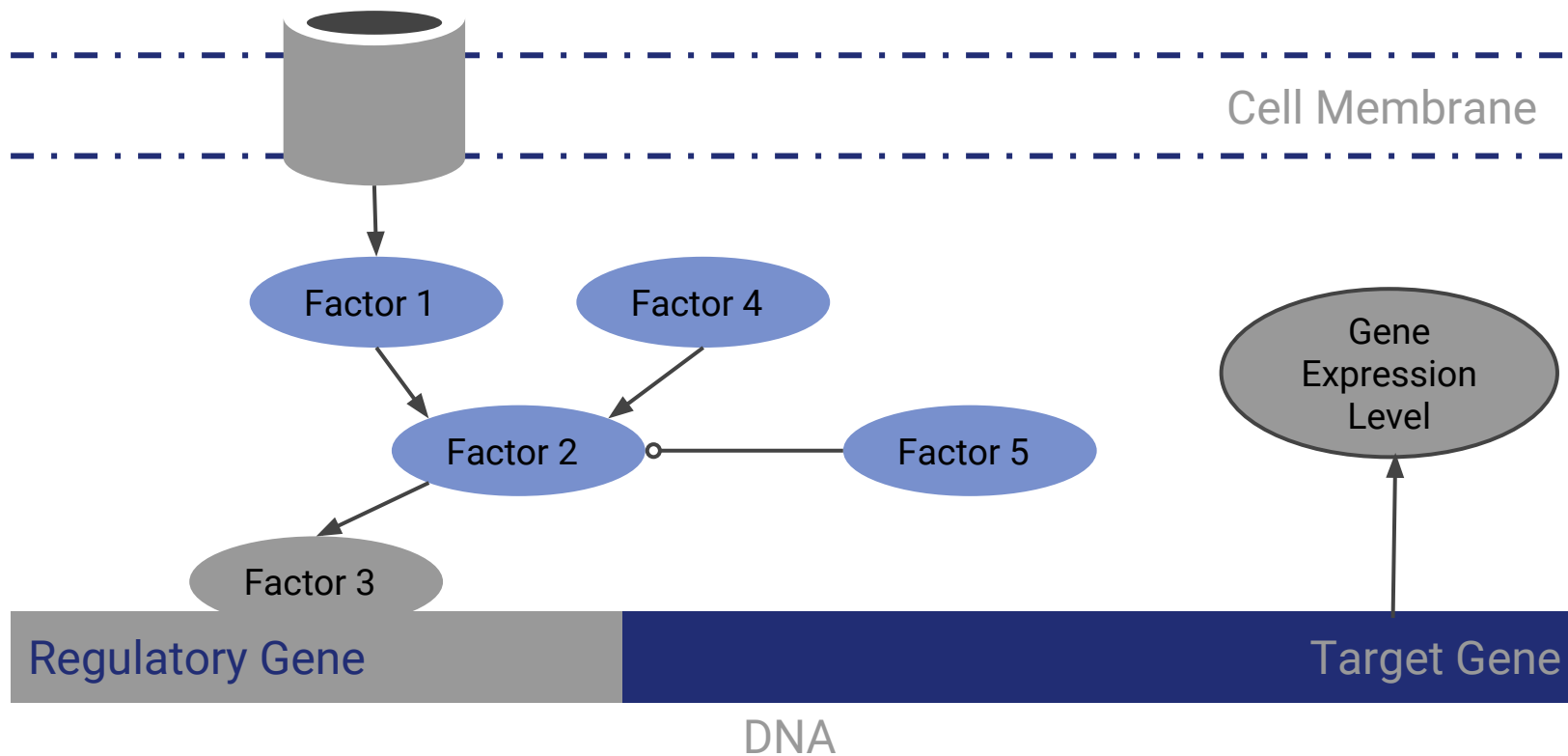
Advisors

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Reintroducing the GRN Problem



Where BTP1 finished...

- Correlation $\rho(X, Y) = \frac{\text{cov}(X, Y)}{\sigma_X \sigma_Y}$
- Granger Causality $x_t = a_0 + \sum_{i=1}^m a_i x_{t-i} + \sum_{i=1}^q b_i y_{t-i} + \epsilon_t$
- Mutual Information $I(X, Y) = H(X) - H(X|Y)$
- Transfer Entropy $T(X, Y) = T_{Y \rightarrow X} = H(X_t | X_{t-1:t-d}) - H(X_t | X_{t-1:t-d}, Y_{t-1:t-d})$

Parameters: Size, quantisation, time, lag

Asides: Grid Search, Laplace Smoothing

TE ~ MI > GC > CO

... is where BTP2 picks up

	Linear	Non Linear
Non Predictive	Correlation	Mutual Information
Predictive	Granger Causality	Transfer Entropy

As Random Variable

Convergent Cross Mapping

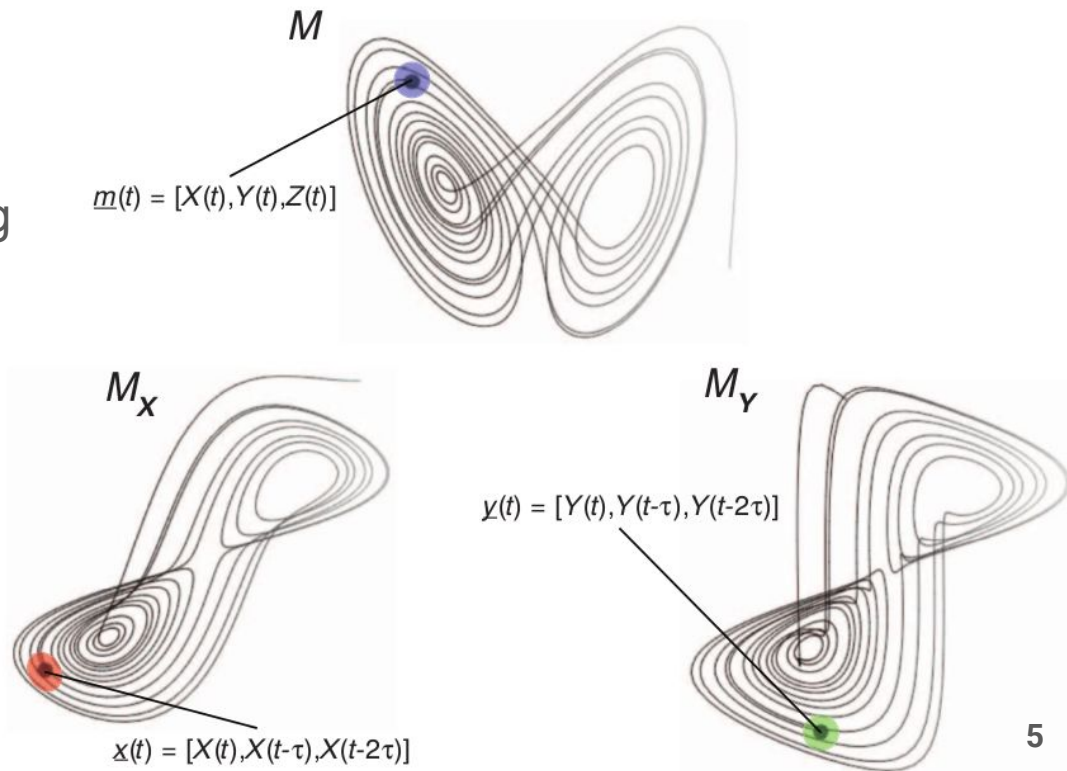
As Dynamical System

Convergent Cross Mapping [Sugihara et al. 2012]

Diffeomorphism across Shadow Manifolds

- For weakly coupled dynamical systems
- New notion of causality: belonging to same dynamical system
- Library size \propto Time series length
- Parameters:
 - Dimensions: M , E where $E \geq M$
 - Lag: τ

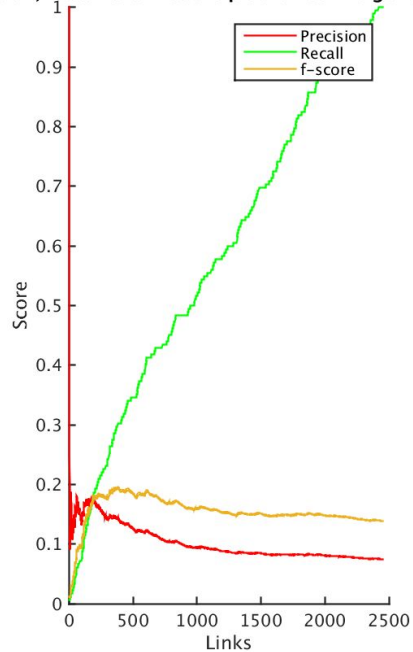
$$C(X, Y) = \rho(X, \hat{X}_Y)$$



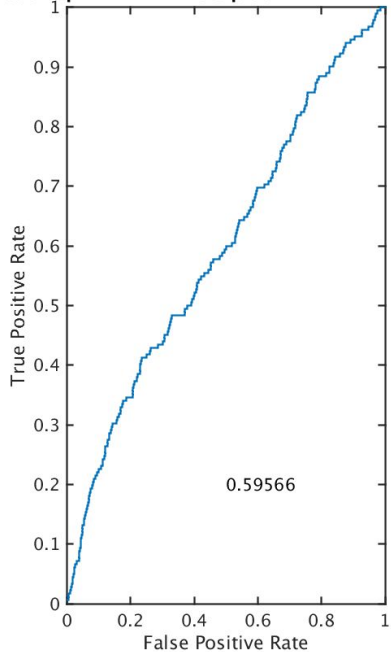
Convergent Cross Mapping

Some Results

Precision, Recall and f-score plot for:ConvergentCrossMap

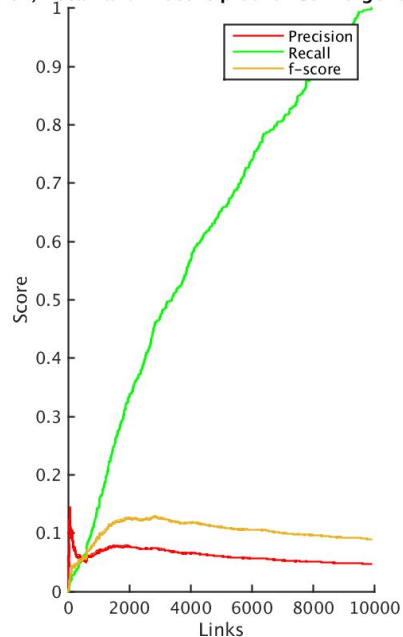


ROC plot

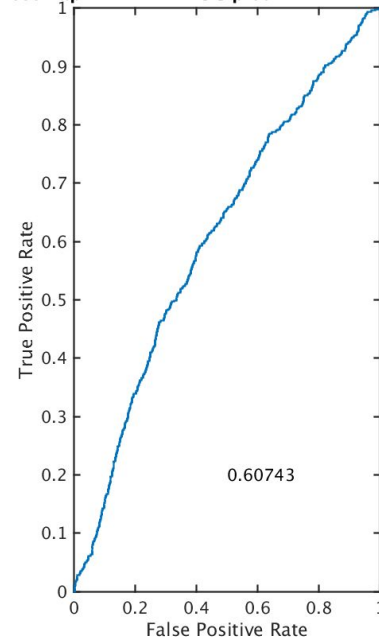


Network Size 50, Time Series Length = 500

Precision, Recall and f-score plot for:ConvergentCrossMap



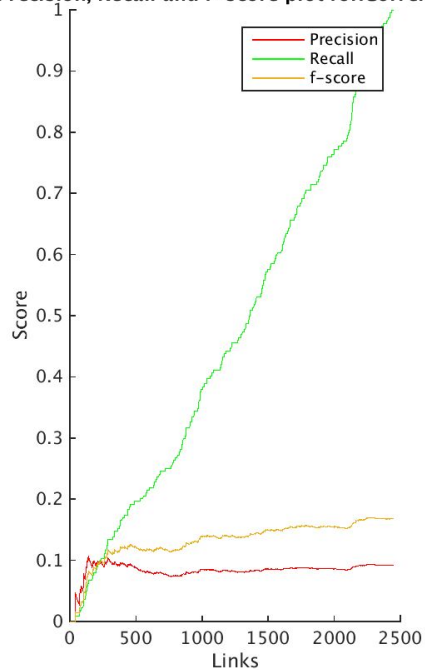
ROC plot



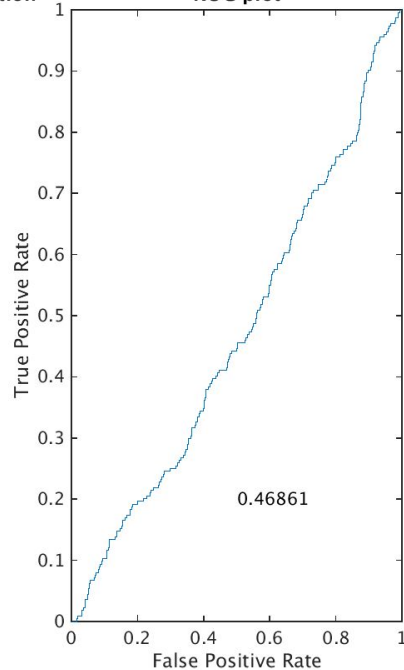
Network Size 100, Time Series Length = 500

Normalisation should be the norm!

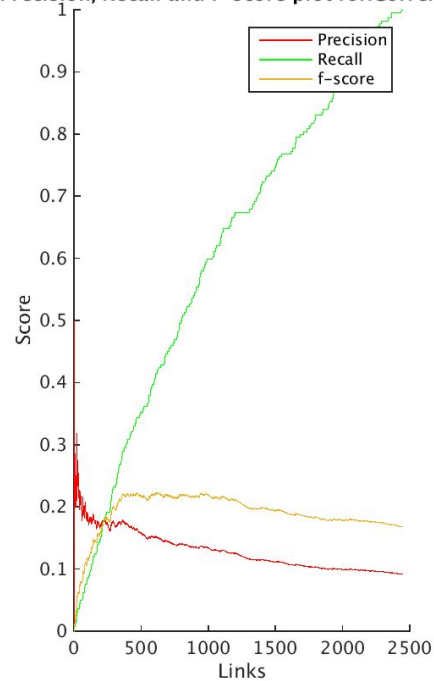
Precision, Recall and f-score plot for:Correlation



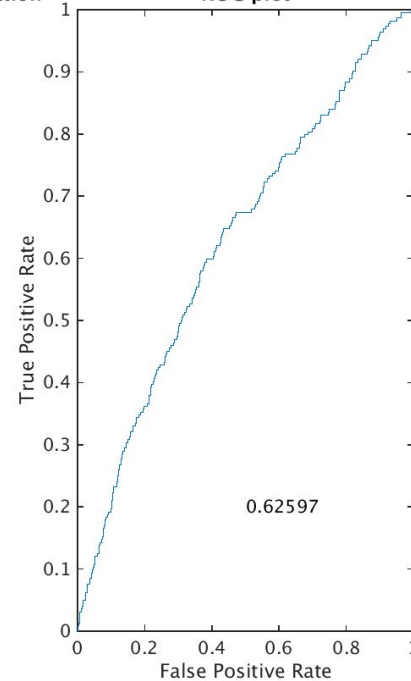
ROC plot



Precision, Recall and f-score plot for:Correlation



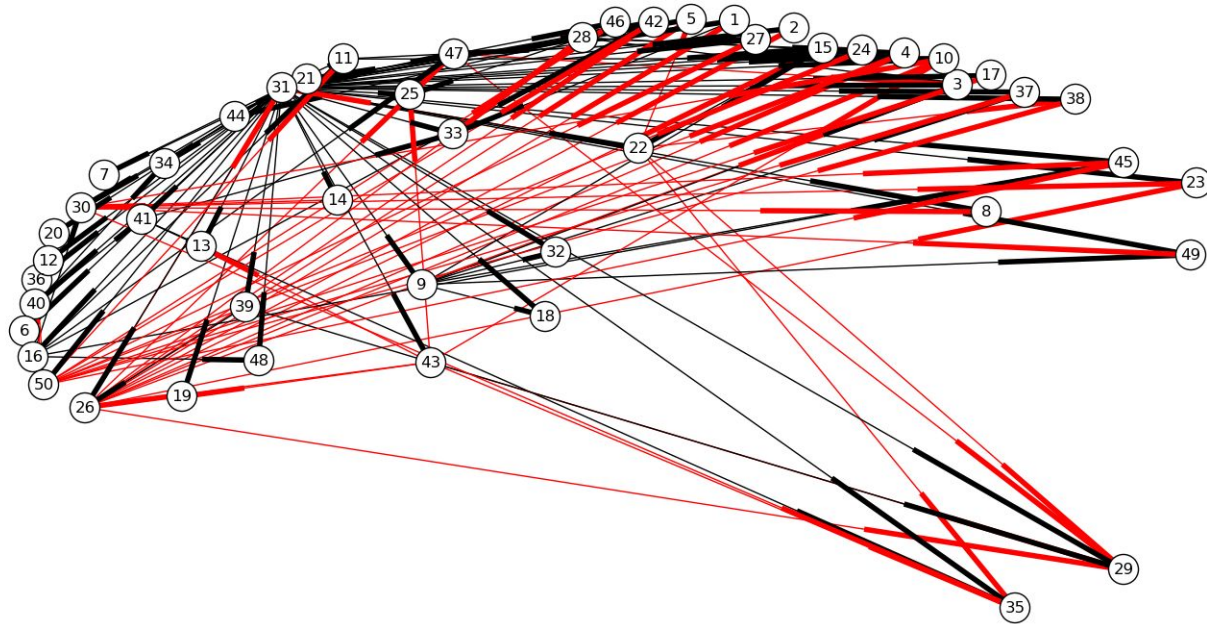
ROC plot



Network Size 50, Time Series Length = 1000

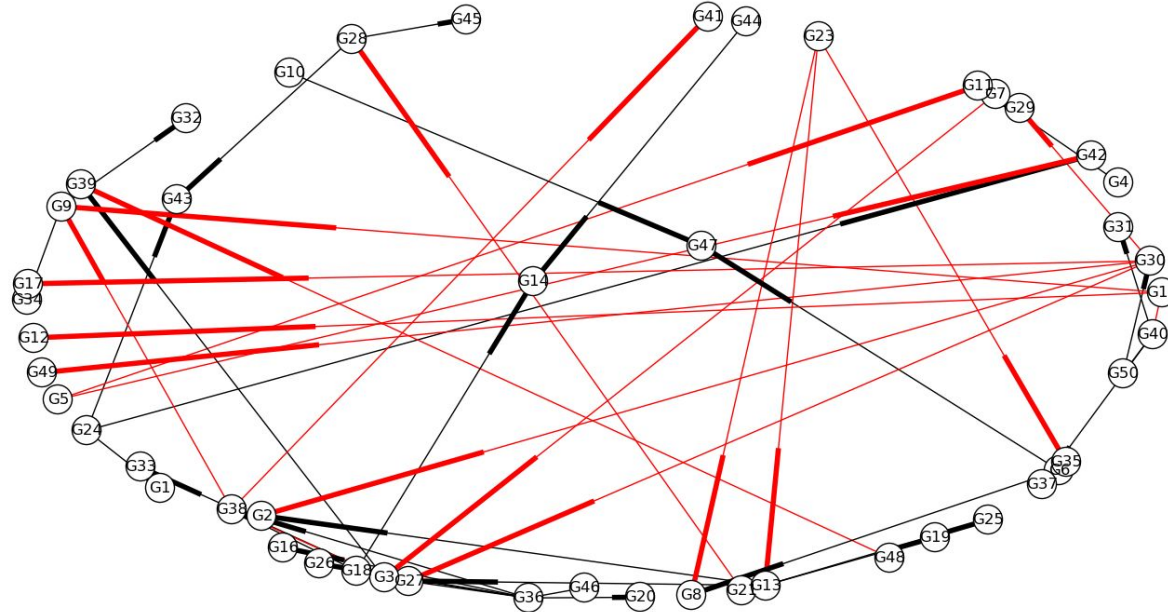
Normalised Time Series data

High degrees are degrading!



Network Size 50, Average Degree = 7

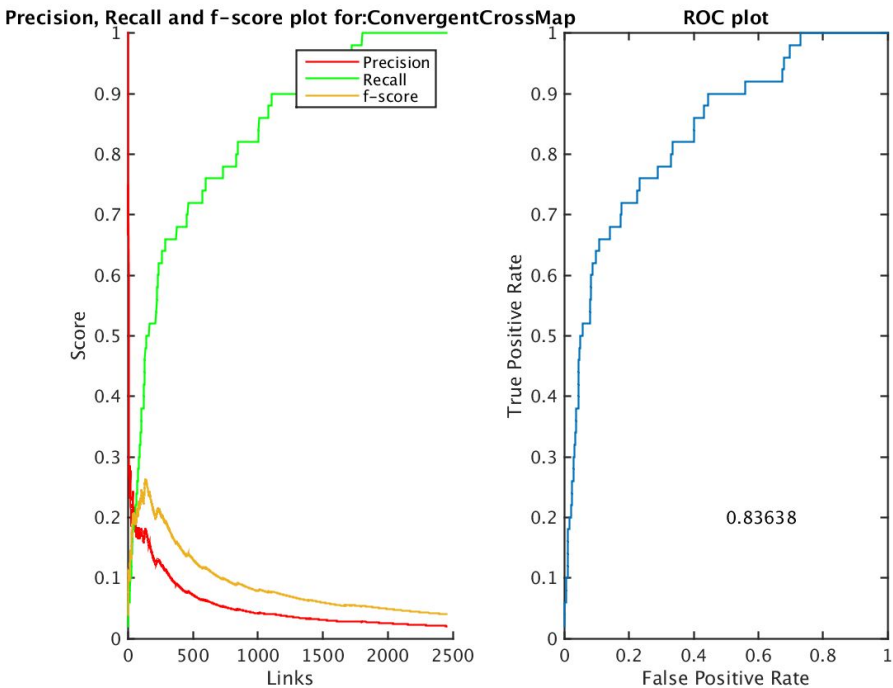
High degrees are degrading!



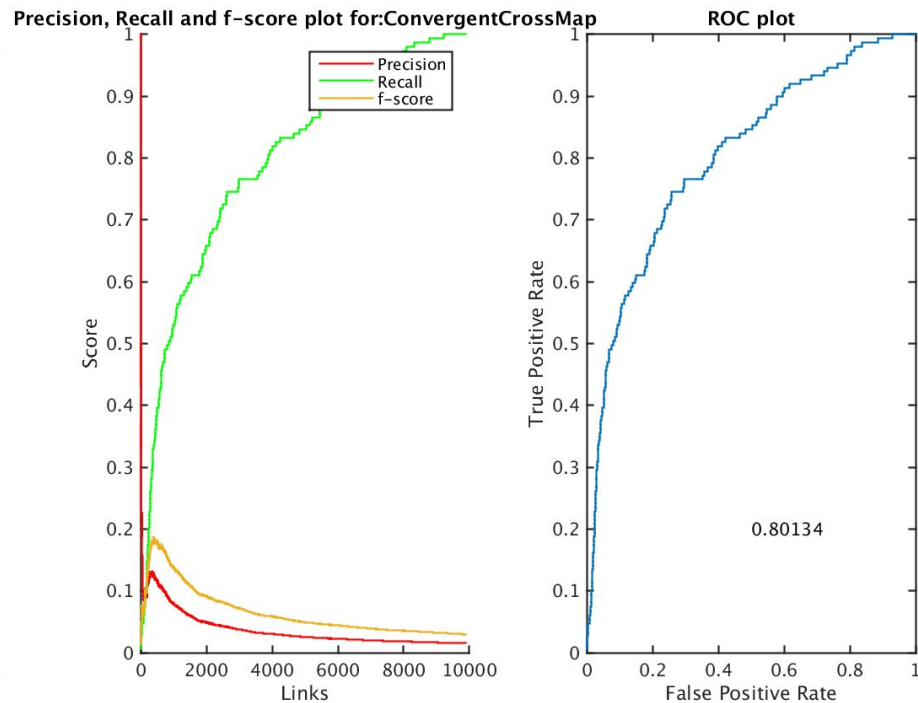
Network Size 50, Average Degree = 2

Convergent Cross Mapping

Some Results



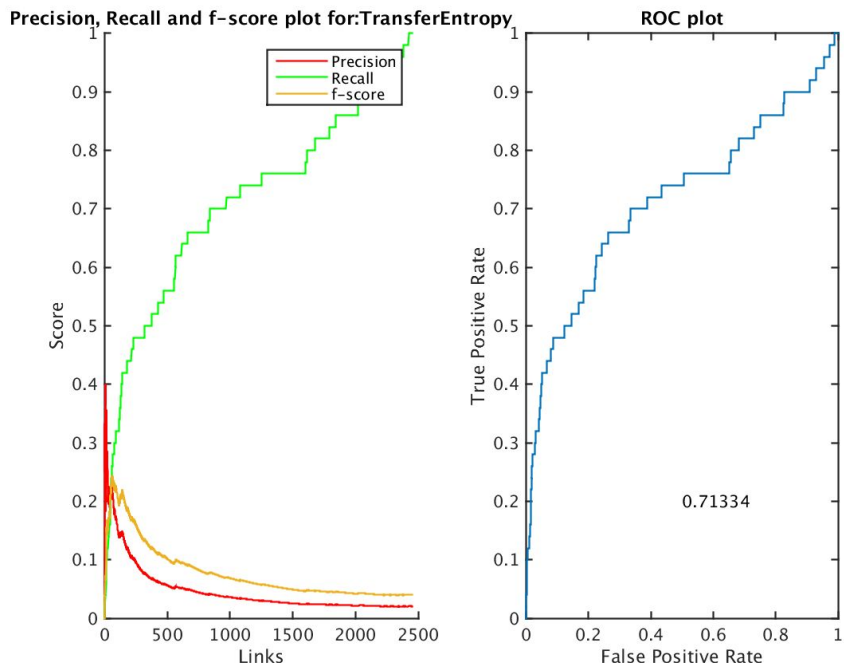
Network Size 50, Time Series Length = 1000



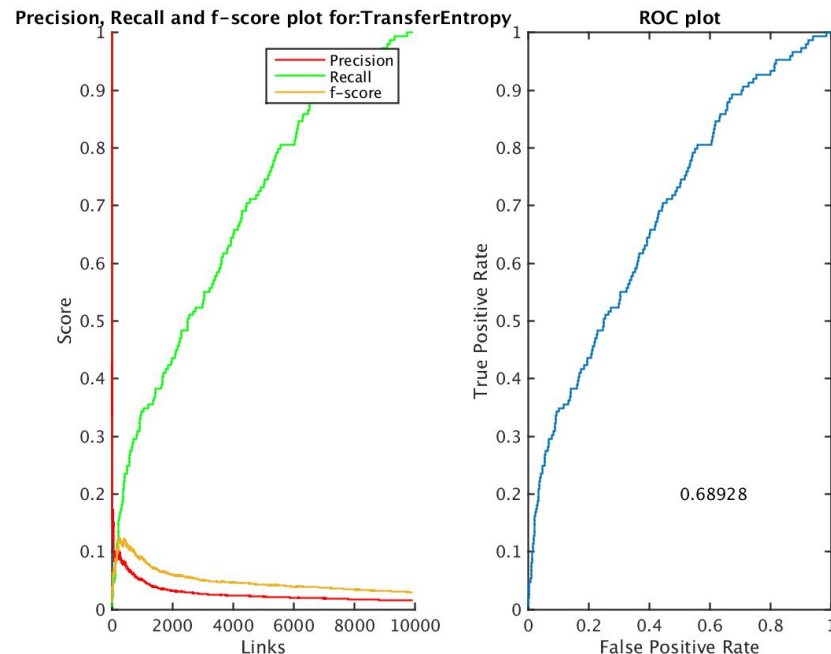
Network Size 100, Time Series Length = 1000

Transfer Entropy

Some Results



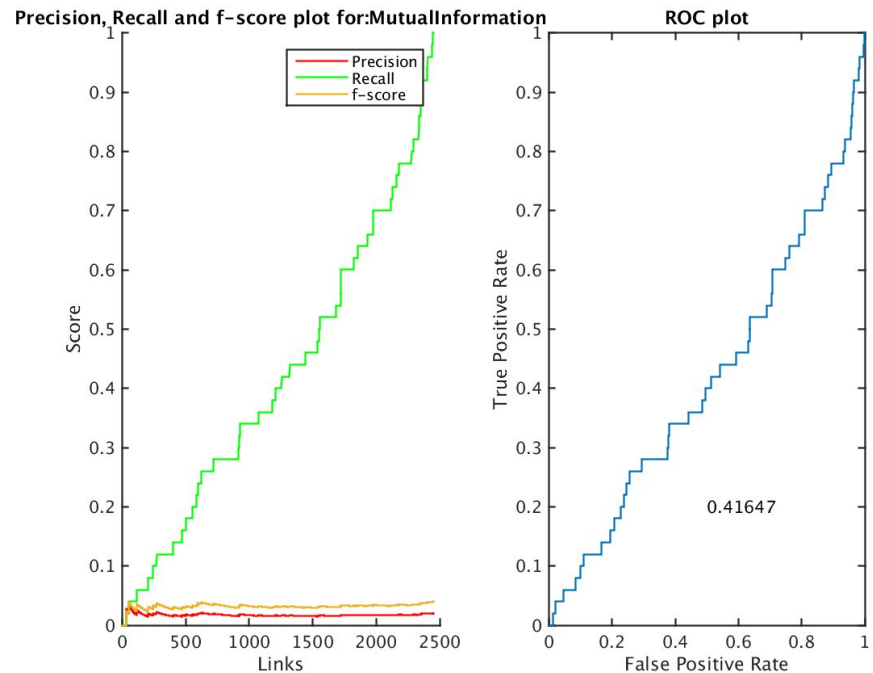
Network Size 50, Time Series Length = 1000
Quantization Level = 10



Network Size 100, Time Series Length = 1000
Quantization Level = 10

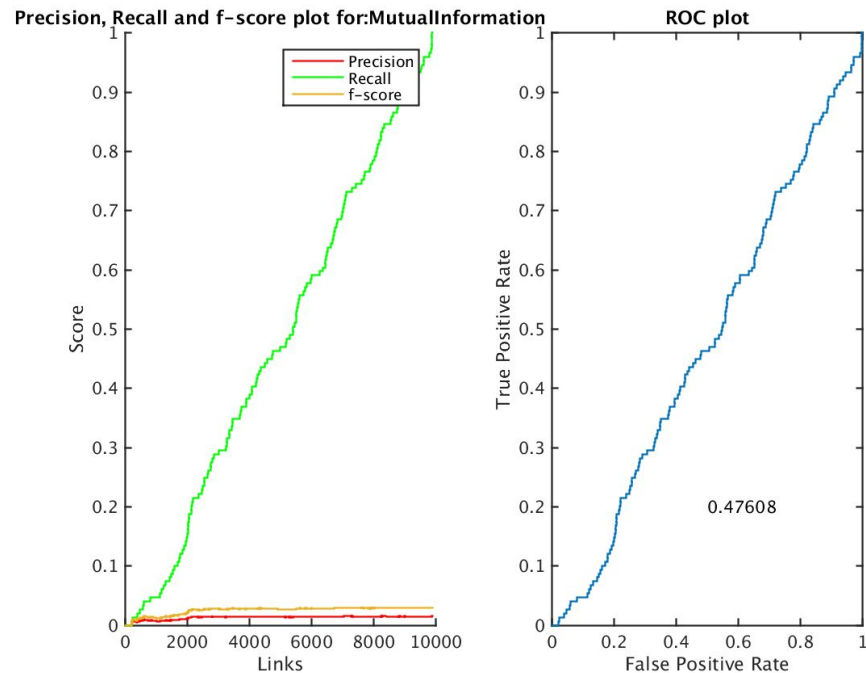
Mutual Information

Some Results



Network Size 50, Time Series Length = 1000

Quantization Level = 10

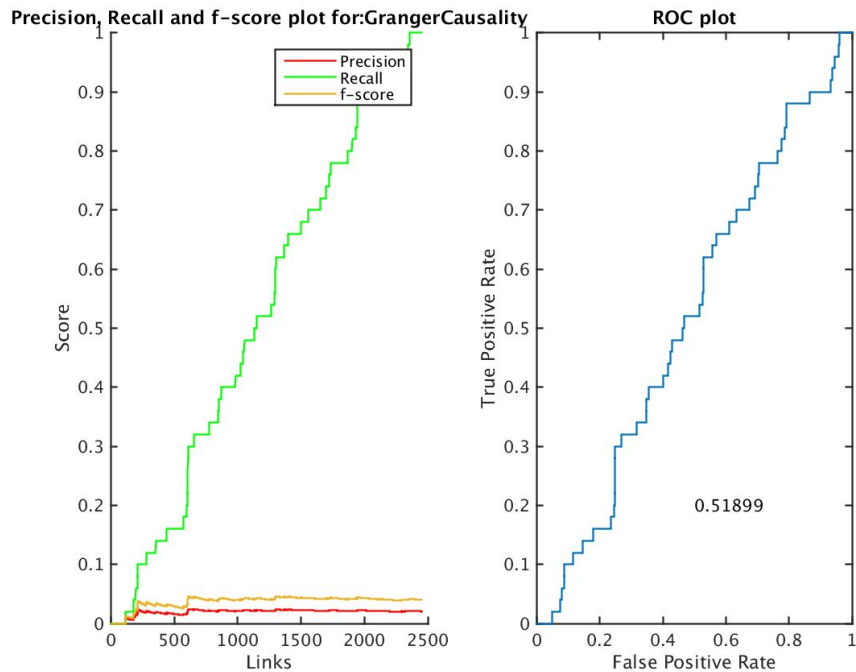


Network Size 100, Time Series Length = 1000

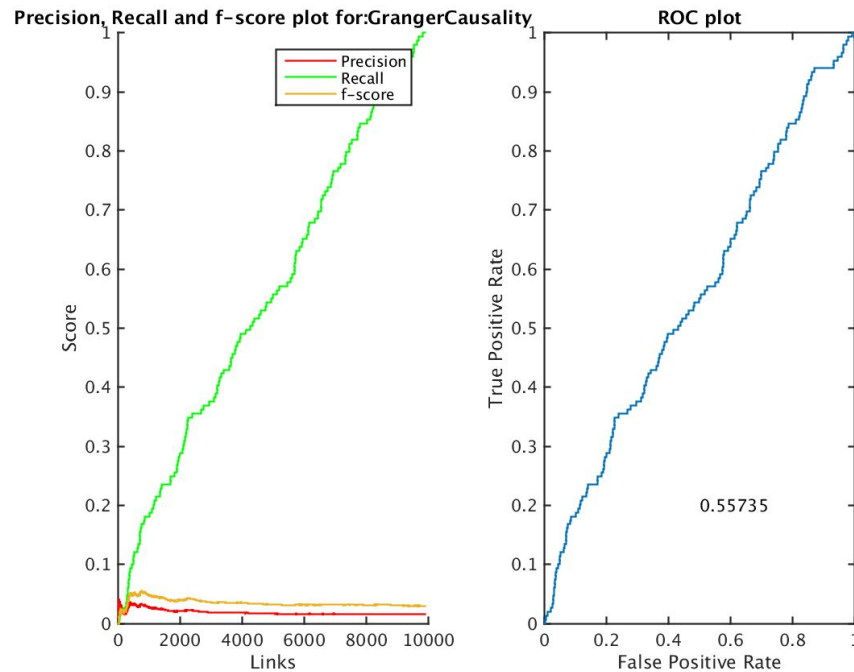
Quantization Level = 10

Granger Causality

Some Results



Network Size 50, Time Series Length = 1000

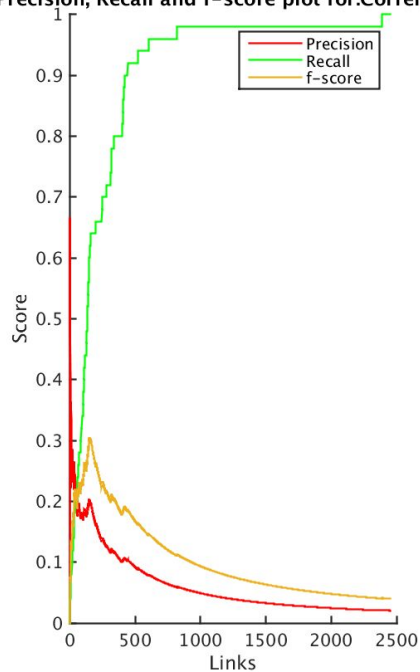


Network Size 100, Time Series Length = 1000

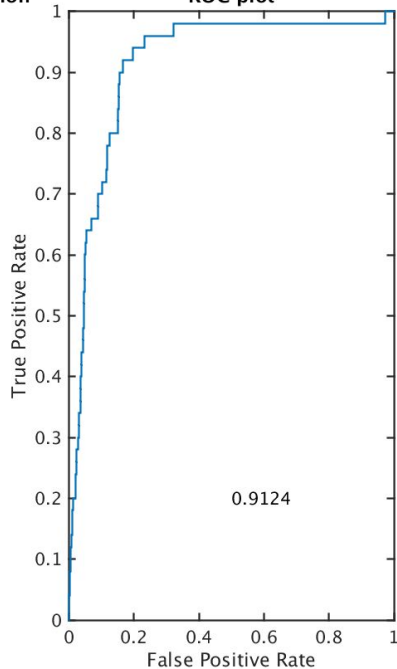
Correlation

Some Results

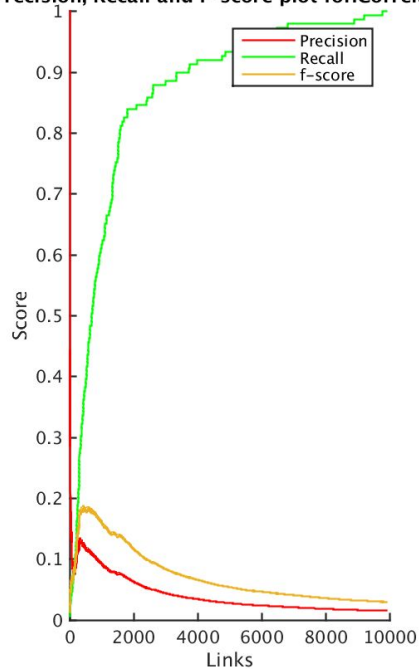
Precision, Recall and f-score plot for:Correlation



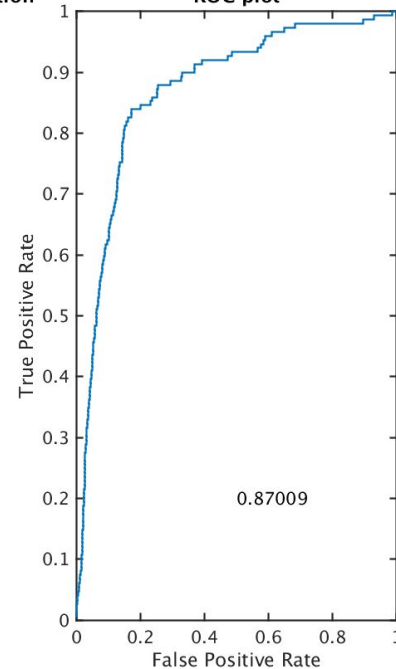
ROC plot



Precision, Recall and f-score plot for:Correlation



ROC plot



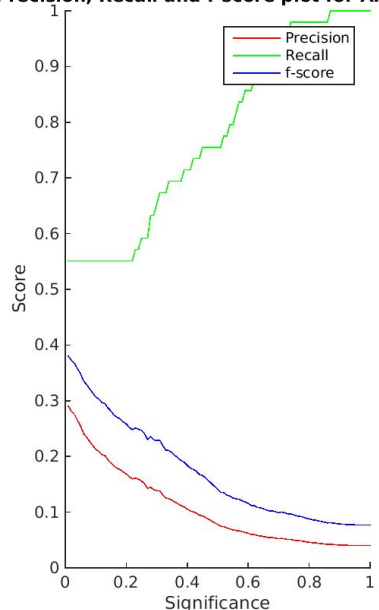
Network Size 50, Time Series Length = 1000

Network Size 100, Time Series Length = 1000

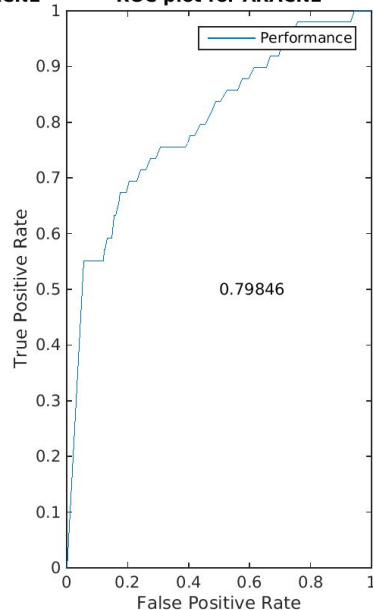
ARACNE [Margilin et al. 2006]

Graph Structure Estimation

Precision, Recall and f-score plot for ARACNE

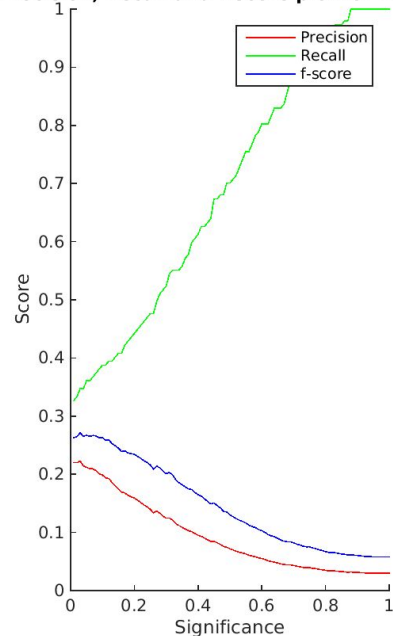


ROC plot for ARACNE

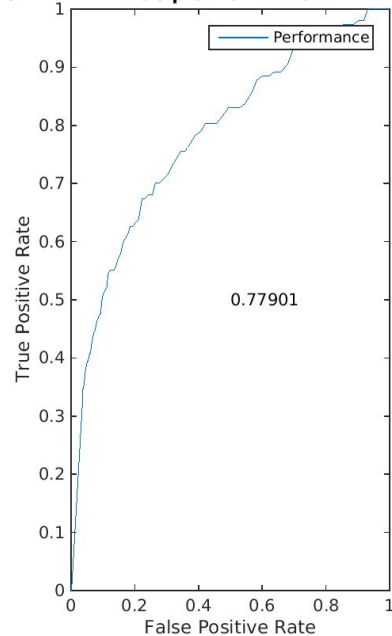


Network Size 50, Time Series Length = 1000

Precision, Recall and f-score plot for ARACNE



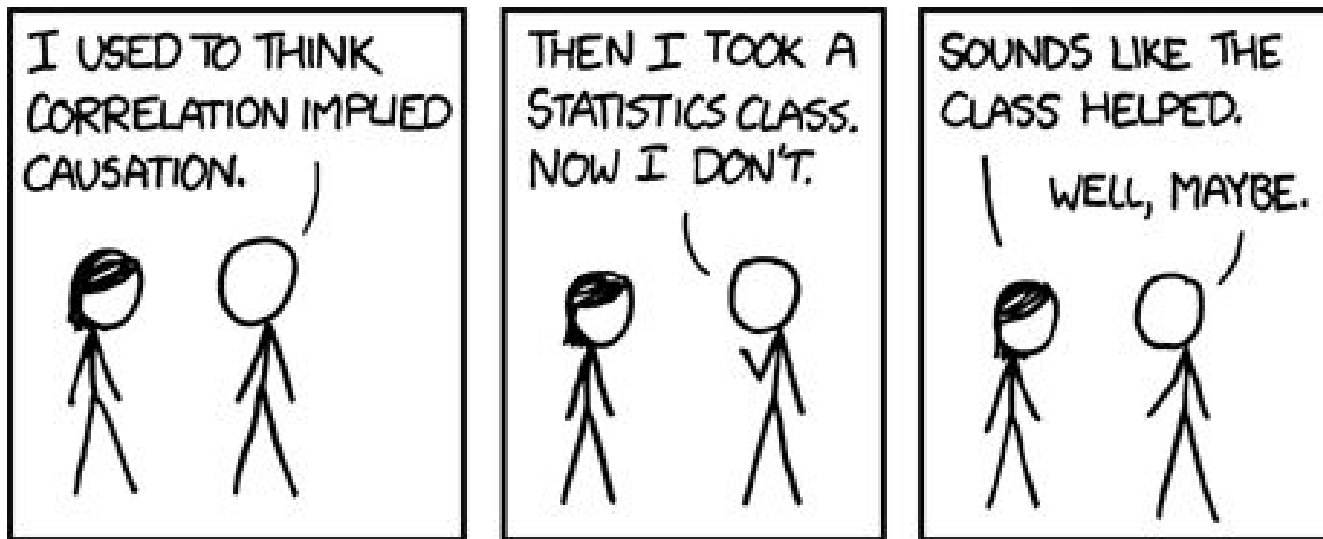
ROC plot for ARACNE



Network Size 100, Time Series Length = 1000

Pairwise Metrics of Causality

A Summary



CCM and Correlation *seem* to work the best at a pairwise level

Naive Edge Selection

1. (Since all pairwise metrics are directly proportional to the strength of causality,) sort ${}^n\text{C}_2$ edges by metric value in decreasing order.
2. Choose top-k edges and output as graph G.

Smart Edge Selection

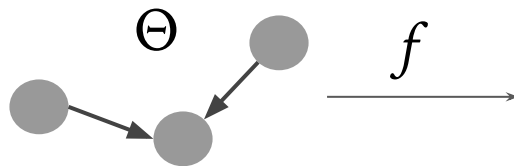
Future Work

Use a “sophisticated” algorithm which selects top-k edges, by making use of graph connectivity and other constraints information.

Intrinsic Graph Structure Estimation [Hino et al. 2015]

Adjacency Matrix to Observation Matrix

$$f : \mathbb{R}^{n \times n} \rightarrow \mathbb{R}^{n \times n}$$



$$\Theta \mapsto f(\Theta) = \Xi$$

Ξ

	—	∩
∩		∩
∩	—	

(Pairwise Metrics used here)

$$\xi_{ij} = c_i + c_{ij}\theta_{ij} + \sum_{k \in V} c_{ij}^k \theta_{ik} \theta_{kj} + \sum_{k, l \in V} c_{ij}^{kl} \theta_{ik} \theta_{kl} \theta_{lj} + \dots$$

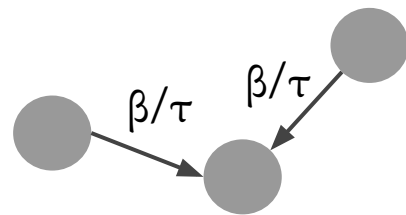
$$t_{ij} = \xi_{ij} + \epsilon$$

Intrinsic Graph Structure Estimation [Hino et al. 2015]

The Random Walk Model

$$L(\Theta) = \begin{bmatrix} \sum \theta_{1k} & -\theta_{12} & \dots & -\theta_{1n} \\ -\theta_{21} & \sum \theta_{2k} & \dots & -\theta_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ -\theta_{n1} & -\theta_{n2} & \dots & \sum \theta_{nk} \end{bmatrix}$$

Digraph
Laplacian



$$f(\Theta) = \alpha e^{\beta L(\Theta)}$$

$$\rho = \{\alpha, \beta\}$$

Intrinsic Graph Structure Estimation [Hino et al. 2015]

Parameter Estimation Algorithm

$$J(\rho, \Theta) = \sum_{i,j \in V, i \neq j} \left(t_{ij} - [f(\Theta)]_{ij} \right)^2$$

In an EM style algorithm, iterating over k (number of edges in graph):

$$\Theta^k = f^{-1}(\Xi)$$

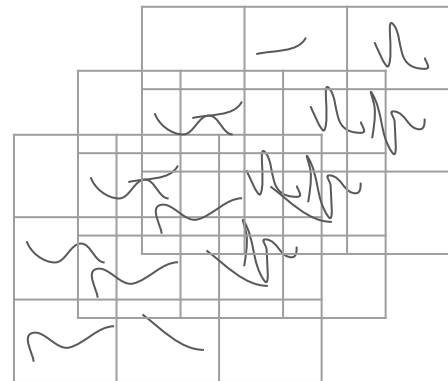
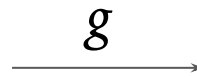
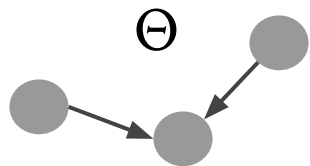
$$\rho_k = \arg \min_{\rho} J(\rho, \Theta^k)$$

Intrinsic Graph Structure Estimation

Moving towards Multi-attribute Data

$$g : \mathbb{R}^{n \times n} \rightarrow \mathbb{R}^{n \times n \times r}$$

$$\Theta \mapsto g(\Theta) = \Xi$$



(Multiple Pairwise Metrics used here)

$${}^q\xi_{ij} = {}^q c_i + {}^q c_{ij} \theta_{ij} + \sum_{k \in V} {}^q c_{ij}^k \theta_{ik} \theta_{kj} + \sum_{k, l \in V} {}^q c_{ij}^{kl} \theta_{ik} \theta_{kl} \theta_{lj} + \dots$$

$${}^q t_{ij} = {}^q \xi_{ij} + \epsilon$$

Intrinsic Graph Structure Estimation

Moving towards Multi-attribute Data

$$g(\Theta) = \text{cat}({}^1 f(\Theta), {}^2 f(\Theta), \dots, {}^r f(\Theta))$$

$$J(\rho, \Theta) = \sum_{1 \leq q \leq r} \left(\sum_{i, j \in V, i \neq j} \left({}^q t_{ij} - {}^q [g(\Theta)]_{ij} \right)^2 \right)$$

$$\Theta^k = \frac{\sum_{1 \leq q \leq r} {}^q f^{-1}(\Xi)}{r}$$

$${}^q \rho_k = \arg \min_{\rho} J(\rho, \Theta^k)$$

Ideally, Θ should be exactly mapped by every ${}^q f^{-1}(\Xi)$

Intrinsic Graph Structure Estimation

More Considerations & Postprocessing

- Imposing extra constraints on Θ
- Explore different ways to map g to Θ (hard versus soft constraints)
- For reduced computational complexity, use a small window of k
- Further postprocessing: Data Processing Inequality

$$g_1 \leftrightarrow \dots \leftrightarrow g_2 \leftrightarrow \dots \leftrightarrow g_3$$

$$I(g_1, g_3) \leq \min[I(g_1, g_2), I(g_2, g_3)].$$

Thank You

Questions and Feedback